

Strategic Protection Against Data Injection Attacks on Power Grids

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Outline

- This talk is to understand
 - false data injection attacks on state estimation in power grids
 - some protection strategies against these attacks

Power System State Estimation

- Monitor the power flow in the power system
- Consider a linearized measurement model

$$\mathbf{z} = \mathbf{H}\theta + \mathbf{n}$$

- $\mathbf{z} \in \mathbb{R}^M$ is the vector of measurements
 - $\theta \in \mathbb{R}^N$ is the state vector
 - $\mathbf{H} \in \mathbb{R}^{M \times N}$ is the measurement Jacobian matrix
 - \mathbf{n} is the vector of measurement noise
- The estimated state vector

$$\hat{\theta} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H} \mathbf{z}$$

Bad Measurement Detection

- Bad measurement can exist due to meter failures, malicious attacks, etc.
- The common approach to detect the bad measurement is to use the statistical testing on $\|\mathbf{z} - \mathbf{H}\hat{\boldsymbol{\theta}}\|_2$
 - if $\|\mathbf{z} - \mathbf{H}\hat{\boldsymbol{\theta}}\|_2 > \mu$, the bad measurement is present
- Let $\mathbf{z}_b = \mathbf{z} + \mathbf{x}$ and $\hat{\boldsymbol{\theta}}_b = \hat{\boldsymbol{\theta}} + \mathbf{c}$
 - \mathbf{x} is the false data injected by the attacker
 - if $\mathbf{x} = \mathbf{H}\mathbf{c}$,
$$\|\mathbf{z}_b - \mathbf{H}\hat{\boldsymbol{\theta}}_b\|_2 = \|\mathbf{z} - \mathbf{H}\hat{\boldsymbol{\theta}}\|_2$$
 - No bad measurements can be detected !

Main Results

- From the attack modeling viewpoint
 - How to construct \mathbf{c} s.t. $\mathbf{x} = \mathbf{H}\mathbf{c}$?
- From the grid designer's viewpoint
 - How to choose a subset of measurements to protect s.t. the false data injection attacks can be detected ?
 - How to place secure PMUs to protect the state estimation under false injection attacks ?

Attack Modeling

- Let \mathcal{S} be a set of indices of N_S protected measurements
- and $\mathbf{H}^{\mathcal{S}}$ be a submatrix of \mathbf{H} whose rows are indicated by the indices in \mathcal{S}
- The measurement constraint for the attacker

$$\mathbf{H}^{\mathcal{S}} \mathbf{c} = \mathbf{0}$$

- if either $\text{rank}(\mathbf{H}^{\mathcal{S}}) = N$ or there exists N linearly independent measurements, $\mathbf{c} = \mathbf{0}$
- **assumptions**
 - ▶ $\text{rank}(\mathbf{H}^{\mathcal{S}}) < N$
 - ▶ $\|\mathbf{c}\|_{\infty} \geq \tau$ (small shifts have very small impact on the state estimation). Note $\|\mathbf{c}\|_{\infty} = \max\{|c_1|, \dots, |c_N|\}$

Attack Modeling

- Attacker can find the smallest number of meters to tamper with and their associated indices

$$\begin{aligned} \min_{\mathbf{c}} \quad & \|\mathbf{H}^{\mathcal{S}} \mathbf{c}\|_0 \\ \text{s.t.} \quad & \mathbf{H}^{\mathcal{S}} \mathbf{c} = \mathbf{0} \\ & \|\mathbf{c}\|_{\infty} \geq \tau \end{aligned}$$

- That is, it looks for the sparsest attack vector \mathbf{c}
- $\|\mathbf{y}\|_0$ is the number of nonzero elements in \mathbf{y}

- Equivalently,

$$\begin{aligned} \min_{i=1, \dots, N} \min_{\mathbf{c}} \quad & \|\mathbf{H}^{\mathcal{S}} \mathbf{c}\|_0 \\ \text{s.t.} \quad & \mathbf{H}^{\mathcal{S}} \mathbf{c} = \mathbf{0} \\ & |c_j| \geq \tau \end{aligned}$$

Attack Modeling

- The **inner** minimization problem was shown to be

$$\begin{aligned} \min_{\mathbf{c}_i \in \mathbb{R}^{N-1}} \quad & \|\mathbf{H}_i^{\bar{S}} \mathbf{c}_i + \mathbf{h}_i^{\bar{S}}\|_0 \\ \text{s.t.} \quad & \mathbf{H}_i^S \mathbf{c}_i + \mathbf{h}_i^S = 0 \end{aligned}$$

- Here \mathbf{H}_i^S is \mathbf{H}^S after deleting the i th column \mathbf{h}_i^S
- **NP-hard in general !**

Attack Modeling

- Approach 1:

$$\begin{aligned} \min_{\mathbf{c}_i \in \mathbb{R}^{N-1}} & \quad \|\text{diag}(\mathbf{w}_i)(\mathbf{H}_i^{\bar{S}} \mathbf{c}_i + \mathbf{h}_i^{\bar{S}})\|_1 & (1) \\ \text{s.t.} & \quad \mathbf{H}_i^S \mathbf{c}_i + \mathbf{h}_i^S = 0 \end{aligned}$$

where $\mathbf{w}_i \in \mathbb{R}^{M-N_S}$ and attacker can choose $w_{ik} = \frac{1}{|x_{ik}| + \epsilon}$ for $\epsilon > 0$, $k = 1, \dots, M - N_S$. Remember N_S is the number of protected measurements

- Approach 2:

$$\begin{aligned} \min_{\mathbf{c}_i \in \mathbb{R}^{N-1}} & \quad \|\mathbf{c}_i\|_1 & (2) \\ \text{s.t.} & \quad \mathbf{H}_i^S \mathbf{c}_i + \mathbf{h}_i^S = 0 \end{aligned}$$

Attacker's Strategies

- Combination of both Approach 1 and Approach 2
- In particular, for state i
 - Solve (2) to find an initial \mathbf{c}_i
 - for a fixed number of iterations
 - ▶ Compute $\mathbf{x}_i = \mathbf{H}_i^{\overline{S}} \mathbf{c}_i + \mathbf{h}_i^{\overline{S}}$
 - ▶ Find $w_{ik} = \frac{1}{|x_{ik}| + \epsilon}$
 - ▶ Then solve (1) to obtain new \mathbf{c}_i

Protection Strategies

- Under the above attack strategy, the grid designer can
 - Choose a subset of measurements to protect
 - ▶ Which subset should be chosen?
 - Place some secure PMUs into the grid
 - ▶ Where should secure PMUs be placed?

Measurement Subset Selection

- Let N_A be the minimum number of measurements that the attacker needs to modify to evade the bad data detection
- The injected data to the i th state

$$\mathbf{x}_i = \mathbf{H}_i^{\bar{S}} \mathbf{c}_i^* + \mathbf{h}_i^{\bar{S}}$$

where \mathbf{c}_i^* is the best possible attack vector modifying at least the i th state

- The goal

$$\begin{aligned} \min_{\mathcal{S}} |\mathcal{S}| & \quad (3) \\ \text{s.t.} \quad \min_i \|\mathbf{x}_i\|_0 & \geq N_A \end{aligned}$$

Subset Selection Algorithm

- Initialize $\mathcal{S} = \emptyset$
- While $\|\mathbf{x}_i\|_0 < N_A$ for all $i = 1, \dots, N$
 - generate an array $\mathbf{\Gamma}$ of M elements that count the number of times each measurement is modified under the attack ($\mathbf{\Gamma} = \mathbf{0}$ initially)
 - for each state
 - ▶ solve (3) to find \mathcal{S}_i and $\|\mathbf{x}_i\|_0$
 - ▶ update $\mathbf{\Gamma}$ by adding one unit to the elements of $\mathbf{\Gamma}$ with indices in \mathcal{S}_i if $\|\mathbf{x}_i\|_0 < N_A$
 - find the measurement that is modified the most and add it into \mathcal{S}

Secure PMU placement

- Adding additional PMUs into the grid modifies the measurement Jacobian matrix \mathbf{H} in the original model
- Let $\bar{\mathbf{H}}_k$ be Jacobian matrix associated with adding a secure PMU to bus k , $k = 1, \dots, N$

- For the attacker

$$\begin{pmatrix} \mathbf{H}^S \\ \bar{\mathbf{H}}_k \end{pmatrix} \mathbf{c} = 0$$

- Given \mathbf{c}_i^* , the goal is to find a bus to place an EPU s.t.

$$\bar{\mathbf{H}}_k \mathbf{c}_i^* \neq 0$$

- adding an PMU must force the attacker to find another solution \mathbf{c}

Secure PMU placement Algorithm

- While $\|\mathbf{x}_i\|_0 < N_A$ for all $i = 1, \dots, N$
 - Initialize a count array $\mathbf{\Delta}$ of N elements that counts the number of times that adding new secure PMUs can help ($\mathbf{\Delta} = 0$)
 - For each state
 - ▶ find \mathbf{c}_i^* and $\|\mathbf{x}_i\|_0$
 - ▶ if $\|\mathbf{x}_i\|_0 < N_A$,

$$\mathbf{\Delta}(k) = \mathbf{\Delta}(k) + \mathbb{I}(\overline{\mathbf{H}}_k \mathbf{c}_i^* = 0)$$

- Find $k^* = \arg \max_k \mathbf{\Delta}(k)$
- Update \mathbf{H}^S to $\begin{pmatrix} \mathbf{H}^S \\ \overline{\mathbf{H}}_{k^*} \end{pmatrix}$

Simulations

- Consider the \mathbf{H} matrices for standard IEEE test systems (IEEE 30-bus, 57-bus, 118-bus, and 300-bus)
- Evaluation metrics
 - The min number of measurements attacker needs to manipulate to pass the detection v.s. the fraction of measurements being protected
 - The min number of meters attacker needs to manipulate to pass the detection v.s. the fraction of buses having secure PMUs placed
- Refer to the paper for the numerical simulation results for both algorithms

Discussion

- One attack at a time. The attack model can be modified to deal with the attacks to multiple states
 - However, the optimization problem may be infeasible
 - Hence, an alternative attack modeling needs investigating
- In the measurement subset selection algorithm, only one measurement is chosen to protect at one time. Is there any approach to choose multiple measurements to protect at one time?
- Grid topology changes such as line outages, meter failures, meter adding, etc.
 - The new algorithms are worthy investigating to incorporate the dynamics of the power grid